



Code the Future

Tinkering and Robotics

1st Joint Staff Training 9th-13th December 2019 - I.T.T. Malafarina Soverato, Italy - by ing.Franco Babbo

What "tinkering" means ...

Tinkering is a "Learn by Doing" method

to make learning fun



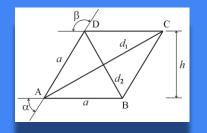
FUN

What "tinkering" means ...

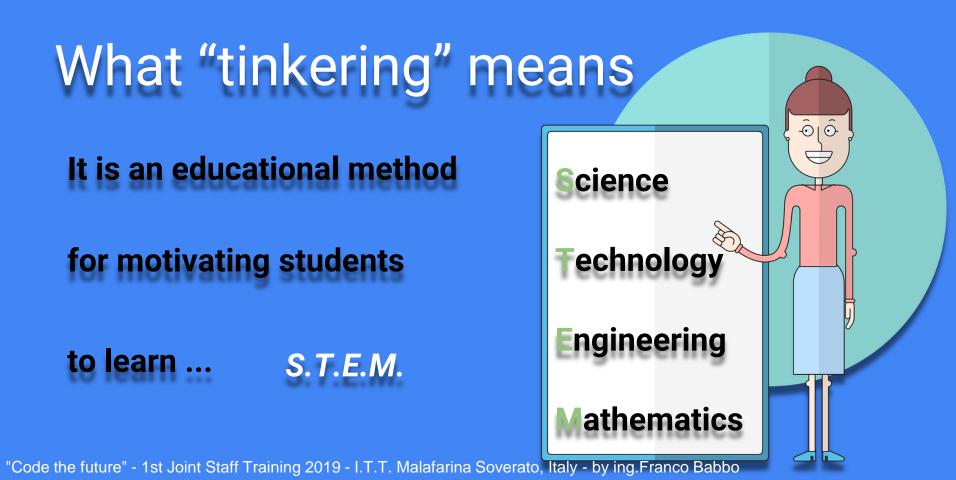
to understand

... just to say ;) ...

a geometry concept ...



without knowing geometry...



and know ...

what "robotics" means ...



... at school

to explain this ... let's take a look at what "robotics" means ...



... in our school ...

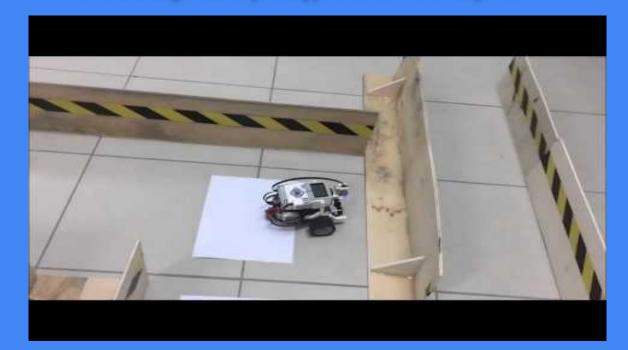


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overal

Lego Mindstorms

this is a Lego based prototype that solves a labyrinth



these legs are produced using Lego components

but they're controlled by an Arduino electronic board

using a microphone we can make the legs dance ...



this is a six-motor robotic arm

we control it using a gyroscope connected to an Arduino



so the robotic arm follows the hand movements

at the end of this presentation we will see the prototype in action in the Telecommunication lab



orso La Robotica con Arduino - ITT Malafarina Soverato - A.S.2016/17 - ing Franco Babbo

this is an example of a real time interaction between an Arduino board and a computer



using a gyroscope connected to an Arduino board we can control the movement of a 3d object on the screen

the draw is obtained using the Processing software



Arduino in Robotics

in this Arduino board based system we can control the rotation of an asyncronous 1000w motor using a smartphone



this is a domotic home Arduino based prototype

we can:

Arduino in Domotics

- turn on and off lights through a proximity sensor
- play and stop music through proximity sensors
- control some applications using an Internet browser

we have developed it for the thirty-year anniversary of our institute

at the end of this presentation we will see the prototype in action in the Telecommunication lab



this is the 3rd step of an Erasmus project "smart-i"

It's a robotics irrigation system

Lego and Arduino in Robotics

when a plant needs water sends a radio signal to the robot that recognizes and irrigates it

the robot stops irrigating when the plant needs no more water and sends a second radio signal

this prototype will be ready by next year on March

many other functionalities will be implemented ...

at the end of this presentation we will see the 4th step version of it in the Telecommunication lab



...at ITT Malafarina

S4A

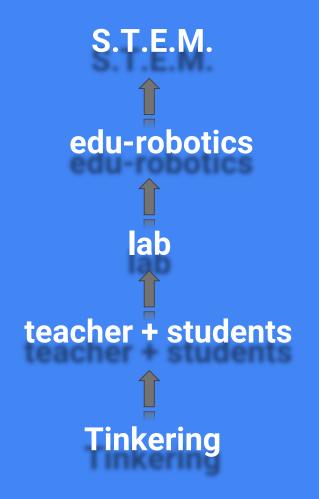
Lego and Arduino in Robotics

Scratch for Arduino

This is an example of interaction between the computer and the real world using S4A software and the Arduino board



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thanks for your attention ...

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