

KATUN Model 3asa


This is the model that we have built in class with components of other rollcoasters.

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Given:
$\mathrm{m}=24,02 \mathrm{~g}$
Ybeginning $=1,02 \mathrm{~m}$
Ytop looping $=0,55 \mathrm{~m}$
Ybottom looping $=0,20 \mathrm{~m}$
Rlooping $=0,35 \mathrm{~m}$



Ghraps
Sleep tabelkolom naar de geel (horizontale as) of groen (vertical axis) voor trendlijn

| markeringen |  | V |
| :---: | :---: | :---: |
| lijnen |  | $\checkmark$ |
| st) |  | $\square$ |
| as | horiz | vert |
| row | $t$ | $\times$ |
| 0 | 0 | 1,09 |
| 1 | 0,033 | 1,079 |
| 2 | 0,067 | 1,076 |
| 3 | 0,1 | 1,066 |
| 4 | 0,133 | 1,062 |
| 5 | 0,167 | 1,05 |
| 6 | 0,2 | 1,037 |
| 7 | 0,233 | 1,021 |
| 8 | 0,267 | 0,999 |
| 9 | 0,3 | 0,98 |
| 10 | 0,333 | 0,952 |
| 11 | 0,367 | 0,927 |
| 12 | 0,4 | 0,899 |
| 13 | 0,433 | 0,867 |
| 14 | 0,467 | 0,832 |
| 15 | 0,5 | 0,795 |
| 16 | 0,533 | 0,753 |
| 17 | 0,567 | 0,712 |
| 18 | 0,6 | 0,666 |
| 19 | 0,633 | 0,621 |
| 20 | 0,667 | 0,577 |
| 21 | 0,7 | 0,523 |
| 22 | 0.733 | 0.474 |
|  |  | t bewerkb |

$(x(t))$

In order to make these recordings we used a detector given to us by the school.

## POINT A:

The carrel gains an
acceleration from our hand.

$y(t) \rightarrow \operatorname{Epot}(J / k g)$ (at the beginning, in
the middle and at the end)


## POINT C:

The carrel is at the summit of the loop and has the lowest acceleration.

## POINT D:

The carrel has the highest acceleration thanks to the slope of the loop.

## Calculations:

$$
\begin{aligned}
& V_{\text {beginning }}(t=0.033)==0.1140842233 \mathrm{~m} / \mathrm{s} \\
& V_{\text {middle }}(t=0.733)==2.026457007 \mathrm{~m} / \mathrm{s} \\
& V_{\text {end }}(t=1.533)==1.331 \mathrm{~m} / \mathrm{s}
\end{aligned}
$$

The velocity increases until the looping, during the looping it decreases.

$$
\begin{aligned}
& \text { axbeginning }(t=0.067)=4.031922866 \mathrm{~m} / \mathrm{s}^{2} \\
& \text { ax middle }(t=0.733)==2.33157672 \mathrm{~m} / \mathrm{s}^{2}
\end{aligned}
$$

$$
\operatorname{axend}(t=1.500)==11.07687343 \mathrm{~m} / \mathrm{s}^{2}
$$

$E_{\text {kin }}=\left(m^{*} v^{2}\right) / 2$
Ekin beginning $=(24.02$ *
$\left.(0.1140842233)^{2}\right) / 2=$
$0,1563126722 \mathrm{~J}$
Ekin middle $=\left(24.02 *(2.026457007)^{2}\right)$
$/ 2=49,3194013 \mathrm{~J}$
Ekin end $=\left(24.02 *(1.331)^{2}\right) / 2=$


## Epot $=m^{*} g^{*} h$

$$
\text { Epot beginning }(0.067)=24.02 * 9.81 *
$$

$$
1.02=240,348924 \mathrm{~J}
$$

$$
\text { Epot top looping }=24.02 * 9.81 * 0.55=
$$

$$
129,59991 \mathrm{~J}
$$

$\mathrm{E}_{\text {pot bottom looping }}=24.02 * 9.81^{*}$

$$
0.20=47,12724 \mathrm{~J}
$$

$$
\text { Epot middle }(0.733)=24.02 * 9.81 * 0.398=93,7832076
$$

$$
\mathrm{J}
$$

$$
E_{\text {pot end }}(1.500)=24.02 * 9.81 * 0=0
$$

## Emech $=$ Ekin + Epot

$E_{\text {mech beginning }}=0.1563126722+240,348924=$ 240,5052367 J
$E_{\text {mech middle }}=49.3194013+93.7832076=$ $143,1026089 \mathrm{~J}$
Emech end $=21,28+0=21,28 \mathrm{~J}$


Problems scalemodel:
We needed a heavier ball because it needed to make a looping and our looping was big. With a heavier ball, the potential gravitation energy was bigger and that results in a higher velocity. At first it just fell, but with the heavier ball the problem was solved.

Table with energy

|  | $E_{\text {kin }}$ | $E_{\text {pot }}$ | $E_{\text {mech }}$ |
| :--- | :--- | :--- | :--- |
| Beginning | $0,16 \mathrm{~J}$ | $240,35 \mathrm{~J}$ | $240,51 \mathrm{~J}$ |
| Middle | $49,32 \mathrm{~J}$ | $93,78 \mathrm{~J}$ | $143,10 \mathrm{~J}$ |
| End | $21,28 \mathrm{~J}$ | 0 J | $21,28 \mathrm{~J}$ |
| Average | $23,58 \mathrm{~J}$ | $111,38 \mathrm{~J}$ | $134,96 \mathrm{~J}$ |

## Mechanic energy change

The mechanic energy decreases because the ball loses energy because there's friction.


