Team 1 Condida Amista Lucia Arlemos Delara

reset/recover robot

very frequently.

Pilot son

reset robot.

Spanish Challinge Part 1

41	remis De	1919		1400 1
TEAM SPIRIT	1 point	2 points	3 points	4-points
	Mentily			
	AND DESCRIPTION OF THE PARTY OF	Some members are entimologic.	Mensivers are entinusiantic and have fun working together	Mambers are enthusiastic an have fur working together. The team has a clear identity
	Participation		美罗拉斯	THE RESIDENCE
	Participation is not well trainneed. Some contributions are underestimated. Respect	witcoperon is well halanced killhough some members to not syntellosts with ideas.	Familipation is well balanced and most members contribute with dean	Farticipalin is well isolance and all members contribute with ideas
	The state of the s	There are some disagramments but	A STATE OF THE PARTY OF THE PAR	The state of the s
	There are frequent arguments aroung members.	mentions can color their conflicts with little intersention by teachers.	Most members show respect to their peers, teachers, bripers.	All member here respectful a the time towards their peers, seastiers, helpers.
	Collaboration	Check Control of the		Company of the second
	Students are individualistic and competition They are			1
		There is some cooperation between mambers.	Most members are helpful.	All members are helpful and there is a clear synergy.
TEAM WORK	Whomas		\$10 TO \$1	10 C 14 C 15
	Poor time	Pour time management. Some	Cood time garagment. Clear roles, Students can	Excellent time managment and very clear roles. Students can achieve all their
	to the	people do not fulfill their role.	achieve shipotimes.	objectives.
	Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
ROBOT DESIGN	efficience of the first an estimated			
& PROGRAMMING	Mechanic efficiency Many problems with	公司第二次 2000年		
	robot design and accessories make it difficult to fulfill	Some problems with robot design	Good design and good	Excellent use of accessories. The robot design is very
	mission.	/accessories during mission.	usde of accessories.	appropriate for the mission.
	Programmin quality	域的開始部隊與位表的起源	The Capture of the	
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	Innovation	Control of the Control		A SHOW THE RESIDENCE
	The team does not develop any ideas or strategies. A lot of	The team managed to develop		Many original ideas/startegi
	help from teachers is necessary.	some original ideas/strategies with teacher's help.	necessary.	to overcome difficulties with little teacher's help.
The state of the state of the state of	Admiration 1	CONTRACTOR OF STREET	ACCOUNT NAME OF THE OWNER, THE OW	and the second second second second
	CONTRACT PLANAGE CO.			

Pilot occasio

recover/reset robot.

32 points

30 points on

ally needs to Robot performs tasks withou robot. pilot's intervention.

Yanki, Mireia, Kaja, Veronika, Naria Spanish Challenge Part &

TEAM SPIRIT	1 point	2 points	3 points	4 points	
	Identity			Un .	
	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Mambers are enthusiastic and have fan working together. The team has a clear identity.	
	Participation			11/	
	Participation is not		Participation is well		
	well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.	
	Respect				
	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All member are respectful all the time towards their peers, teavhers, helpers.	
	Collaboration			THE REPORT OF THE PARTY OF THE	
	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.	
TEAM WORK	Efficiency				
	Poor time managment. Roles are not clear	Poor time managment. Some people do not fulfill their role.	Good time managment. Clear roles. Students can achieve objectives.	Excellent time managment and very clear roles. Students can achieve all their objectives.	
	Independent work	THE RESIDENCE OF STREET	THE RESERVE OF THE PARTY OF THE	THE PARTY OF THE P	
		Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work	Team can work on its own with very little intervention from teachers.	
ROBOT DESIGN	Maria sule officeration	ACCORDING TO SECURITION OF SEC			
& PROGRAMMING	Mechanic efficiency	Photograph of the Control of the Con	Company of the Control of the Control	A STATE OF THE STA	
	Many problems with robot design and			0	
	accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.	
	Programmin quality				
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.	
	Innovation		1		
	The team does not develop any ideas or strategies. A lot of	team managed to develop	Some original ideas/strategies, although	Many original ideas/startegies	
	help from teachers is necessary.	some original ideas/strategies wit teacher's help.		to overcome difficulties with little teacher's help.	
	Pilot needs to	The same of the sa	1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
	reset/recover robot very frequently.	Pliot sometimes needs to recover, reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.	

Gr Magda Papanastasias Sl Nina Spialmanova Spanish Cha Team Wamber 3 Part 1. Sergio Rinero Umut Kog 2 points 1 point 3 points 4 points Identity Members are enthusiastic Mambers are enthusiastic and and have fun working have fun working together. Very little enthusiasm | Some members are enthusiastic together. The team has a clear identity. Participation is not Participation is well Participation is well balanced. well balanced. Some balanced and most Participation is well balanced Although some members do not and all members contribute contributions are members contribute with underestimated. contribute with ideas. ideas with ideas. Respect There are some disagreements but There are frequent members can solve their conflicts Most members show All members are respectful all arguments among with little intervention by respect to their peers, the time towards their peers, teachers, helpers. teavhers, helpers. members. teachers. Collaboration Students are individualistic and competitive. They are All members are helpful and not capable of helping There is some cooperation one another. Most members are helpful. there is a clear synergy. between members. **TEAM WORK** Efficiency Excellent time managment Good time managment. and very clear roles. Students managment. Roles are Poor time managment. Some Clear roles. Students can can achieve all their people do not fulfill their role. achieve objectives. objectives. not clear. Independent work Team can work on its own Good balance between Teachers have to help Teachers have to provide help on teacher's help and with very little intervention many occasions. autonomous work. from teachers. in excess. ROBOT DESIGN & PROGRAMMING Mechanic efficiency Many problems with robot design and accessories make it Excellent use of accessories. difficult to fulfill Good design and good The robot design is very Some problems with robot design accessories during mission. usde of accessories. appropriate for the mission. mission Programmin quality Too many commands. Difficult to Some commands are difficult to Easy, clear and precise Appropriate commands. understand understand commands. Innovation The team does not develop any ideas or Some original strategies. A lot of The team managed to develop ideas/strategies, although Many original ideas/startegies teacher's intervention is to overcome difficulties with help from teachers is some original ideas/strategies wit necessary. little teacher's help. teacher's help. necessary. Pilot needs to reset/recover robot Pilot sometimes needs to recover/ Pilot occasionally needs to Robot performs tasks without very frequently. reset robot. recover/reset robot. pilot's intervention. yo work 2:40 1 ster fish -5 (
4 items to recycle 55 points

Georgia Provatory

Yasin Burma

Kristina Besslerová

Martinez

TEAM SPIRIT Point 2 points 3 points 4 points

Identity

Members are enthusiastic and have fun working to The team has a clear

Participation.

TEACH OF INCL	Identity	PARCE SELECTION		
	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Mambers are enthusiastic and have fun working together. The team has a clear identity.
	Participation	外对于一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个	44 地区 地名美国	The second second
	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
	Respect		的社员,这些人们可能。这是全	1
	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful al the time towards their peers, teavhers, helpers.
	Collaboration		后是100mm/200mm/190mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/200mm/	The state of the s
	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.
	WANTED AND ADDRESS OF THE PARTY.	THE RESERVE AND ADDRESS OF THE PERSON OF THE		Transferred to the contract of the
TEAM WORK	Efficiency	THE RESERVE OF THE PERSON OF T	在一个人的人的人的人的人的人的人的人的人的人的人的人的人的人的人的人的人的人的人的	
	Poor time managment. Roles are not clear.	Poor time managment. Some people do not fulfill their role.	Good time managment. Clear roles. Students can achieve objectives.	and very clear roles. Students can achieve all their phjectives.
	Independent work		国 一个通过证金	国际
	Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	ream can work on its own with very little intervention from teachers.
ROBOT DESIGN				
& PROGRAMMING	Mechanic efficiency	经	国际的企业	公 (在) () () () () () () () () (
	Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	Programmin quality	TOTAL TO THE STATE OF THE STATE	是是2000年上旬(1910年)	
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	Innovation	一种数据的一个一种的一种,但是一种企业的	医型型型型型型型型	
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/startegi to overcome difficulties with little teacher's help.
	Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	
50	very frequently.	reset robot.	recover/reset robot	pilot's intervention.

40 + 30

Tean 5

Maria Boseh Vicky Dzakova Alindo Gelik Patnyga Zachara Kyriaki Papadopoulou

Spanish Challenge Part 1

TEAM SPIRIT	1 point	2 points	3 points	4 points
	Identity			THE RESERVE TO SELECTION OF THE PERSON OF TH
	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Mambers are enthusiastic and have fun working together. The team has a clear identity.
	Participation	建筑的建筑的 经过时间 医	以前 家下、700年)与100	的特别是《神经》。 15. AGUS
	Participation is not		Participation is well	
	well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
	Respect		問題の一色かり時期に対象	THE RESERVE TO SERVE THE PROPERTY OF THE PERSON OF THE PER
	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teavhers, helpers.
	Collaboration	国际 自己的第三人称形式图像设置		
	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.
TEAM WORK	Efficiency	1. 经产品的 1. 10 10 10 10 10 10 10 10 10 10 10 10 10		
	Poor time	Poor time managment. Some people do not fulfill their role.	Good time managment. Clear roles. Students can achieve objectives.	Excellent time managment and very clear roles. Students can achieve all their objectives.
	Independent work	The state of the s	SERVICE TRACE TO SHOP	· 中国发展等。公共的基础与46元
		Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
ROBOT DESIGN				The second of the second of the second
& PROGRAMMING	Mechanic efficiency	CONTRACTOR OF THE CONTRACTOR O	AND DESCRIPTION OF THE PERSON	二、公司的位为"二、有"生"之外是"
	Many problems with robot design and accessories make it		\ \ \	Excellent use of accessories.
	difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	The robot design is very appropriate for the mission.
	Programmin quality	Traccessories during inission.	disce of accessories.	appropriate for the mission.
	Too many commands.			V
	Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	Innovation	under stand.	Appropriate commands.	rediffications.
	The team does not			1
	develop any ideas or	The beam managed to develop	Some original	Many original ideas (startegie
	strategies. A lot of help from teachers is	The team managed to develop some original ideas/strategies with		Many original ideas/startegies to overcome difficulties with
	necessary.	teacher's help.	necessary.	little teacher's help.
	Autonomation		A STATE OF THE PARTY OF THE PAR	the way have the same
	Pilot needs to reset/recover robot	Pilot sometimes needs to recover/	Pilot occasionally needs to	
	very frequently.	reset robot.	recover/reset robot.	pilot's intervention.

33 Publick

TEAM SPIRIT	1 point	2 points	3 points	4 points
	Identity		THE REAL PROPERTY AND ADDRESS.	
			Members are enthusiastic	Mambers are enthusiastic an
			and have fun working	have fun working together.
	Very little enthusiasm	Some members are enthusiastic.	together.	The team has a clear identity
-	Participation Participation	Some members are endustastic.	together.	The team has a clear identity
	Participation is not		Participation is well	
	well balanced. Some	Participation is well balanced.	balanced and most	Participation is well balance
	contributions are	Although some members do not	members contribute with	and all members contribute
	underestimated.	contribute with ideas.	ideas.	with ideas.
	Respect	reord route with ideas.	Meas.	With Ideas.
	nespece	There are some disagreements but		
	There are frequent	members can solve their conflicts	Most members show	All members are respectful a
	arguments among	with little intervention by	respect to their peers,	the time towards their peers
	members.	teachers.	teachers, helpers.	teavhers, helpers.
	Collaboration	The second secon	No control of the con	The state of the s
	Students are			
	individualistic and			
	competitive. They are			X .
		There is some cooperation	1 (All members are helpful and
	one another.	between members.	Most members are helpful.	
EAM WORK	Efficiency			
				Excellent time managment
	Poor time	- (Good time managment.	and very clear roles. Student
		Poor time managment. Some	Clear roles. Students can	can achieve all their
	not clear.	people do not fulfill their role.	achieve objectives.	objectives.
-	Independent work	Michael Inc. parts has the self-time	Condition on house	
	Touch our house to halo	Touch and have to provide help and	Good balance between teacher's help and	Team can work on its own
	in excess.	Teachers have to provide help or many occasions.	autonomous work.	with very little intervention from teachers.
to all self-the discontinuous	III CACCSS.	many occasions.	addonomous work.	non teachers.
ROBOT DESIGN	Tagle - Lord production			
PROGRAMMING	Mechanic efficiency		STATE OF THE PARTY	
	Many problems with			
	robot design and			
	accessories make it			Excellent use of accessories.
	difficult to fulfill	Some problems with robot design	Good design and good	The robot design is very
	mission.	/accessories during mission.	usde of accessories.	appropriate for the mission-
	Programmin quality			
	Too many commands.			
	Difficult to	Some commands are difficult to		Easy, clear and precise
	understand.	understand.	Appropriate commands.	commands.
	Innovation	Management Services of the Control o	AND REAL PROPERTY.	
	The team does not		Come eniginal	
	develop any ideas or	The team managed to develop	Some original	Manu original (days (started)
	strategies. A lot of help from teachers is	The team managed to develop some original ideas/strategies with	ideas/strategies, although	Many original ideas/startegi to overcome difficulties with
	The state of the s			ittle teacher's help.
	Autonomation	teacher's help.	necessary.	The reaction strong.
	Pilot peeds to			
	Pilot needs to	Pilot sometimes peads to recover/	Pilot occasionally needs to	Robot performs tacks with a
(Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks withou

Table Points: [5]
Rubric Points [35]
Total: 140

EAM SPIRIT	1 point	2 points	3 points	4 points
	Identity	A SECOND PORT OF THE PARTY OF T	THE RESERVE OF THE PERSON OF T	
1			Members are enthusiastic and have fun working	Mambers are enthusiastic and have fun working together
	The same of the sa	Some members are enthusiastic.	together.	The team has a clear identity.
	Participation	设施的重要的证明。	统 的 图代图的 网络印	
	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.		Participation is well balanced and all members contribute with ideas.
	Respect	美国科学区域中国教育社会的政策	是一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个	TO SEE LEVEL TO
	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teavhers, helpers.
	Collaboration	TOTAL TRANSPORT		
	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful	All members are helpful and there is a clear synergy.
TEAM WORK	Efficiency	THE RESIDENCE OF THE PERSON NAMED IN	STATE OF THE STATE	AND THE REAL PROPERTY.
	Poor time	Poor time managment. Some people do not fulfill their role.	Good time managment. Clear roles. Students can achieve objectives.	Excellent time managment and very clear roles. Students can achieve all their objectives.
Approximation of the last of t	Independent work		COLUMN TO SHARE	
		Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
ROBOT DESIGN	b			
& PROGRAMMING	Mechanic efficiency	The state of the s	建设的	A LINE OF THE REAL PROPERTY.
	Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	Programmin quality		第二人员工企业	
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	Innovation		11年1日本の東京の大学の大学の大学の大学	のの地方を記載されている。
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/startegie to overcome difficulties with little teacher's help.
	Autonomation	THE RESERVE OF THE PARTY OF THE		A CHARLES TO THE OWNER.
	Pilot needs to reset/recover robet very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks withou pilot's intervention.

Table points [65]
Rubric points [37]
Total [102]

EAM SPIRIT	1 point	2 points	3 points	4 points
	Identity	Country Francisco Pales	E MARINE TELL	STATE OF THE PARTY
			Members are enthusiastic	Mambers are enthusiastic and
	Tr. bad at a		and have fun working	have fun working together.
	AND REAL PROPERTY AND INCOME.	Some members are enthusiastic.	together.	The team has a clear identity
	Participation	《 	《新》的《大学》,"我们是一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个一个	The second second second
	Participation is not		Participation is well	
	well balanced. Some	Participation is well balanced.	balanced and most	Participation is well balanced
	contributions are	Although some members do not	members contribute with	and all members contribute
	underestimated.	contribute with ideas.	ideas.	with ideas.
	Respect	(E) 在10年 (D) 数据 (E) 在10年 (E)	問題和企業也是開發的學	
		There are some disagreements but		
	There are frequent	members can solve their conflicts	Most members show	All members are respectful all
	arguments among	with little intervention by	respect to their peers,	the time towards their peers,
	members.	teachers.	teachers, helpers.	teavhers, helpers.
	Collaboration		THE PERSON NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TRANSPORT	· 智斯特的 對關於此一個形。
	Students are			
	individualistic and		/	,
	competitive. They are		· /	
	not capable of helping	There is some cooperation		All members are helpful and
	one another.	between members.	Most members are helpful	there is a clear synergy.
	NAME AND ADDRESS OF THE PARTY O	CONTRACTOR OF THE PERSON NAMED IN COLUMN	A STATE OF THE PARTY OF THE PAR	Commence of the commence of th
EAM WORK	Efficiency	电子和电子力型		自己的发展,这种地位的
			l /	Excellent time managment
	Poor time		Good time managment	and very clear roles. Students
		_	1 \	
		Poor time managment. Some	Clear roles. Students can	can achieve all their
	not clear.	Poor time managment. Some people do not fulfill their role.	Clear roles. Students can achieve objectives	can achieve all their shiectives.
			achieve objectives	objectives.
	not clear. Independent work	people do not fulfill their role.	Good balance between	Team can work on its own
	not clear. Independent work Teachers have to help	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention
	not clear. Independent work	people do not fulfill their role.	Good balance between	Team can work on its own
	not clear. Independent work Teachers have to help	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention
and the second second	not clear. Independent work Teachers have to help in excess.	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and	people do not fulfill their role. Teachers have to provide help or	Good balance between teacher's help and	Team can work on its own with very little intervention from teachers.
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it	Teachers have to provide help or many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories.
The second secon	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill	Teachers have to provide help or many occasions. Some problems with robot design	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very
The second secon	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission.	Teachers have to provide help or many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories.
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality	Teachers have to provide help or many occasions. Some problems with robot design	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands.	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission.
The second secon	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission.	Good balance between teacher's help and autonomous work. Good design and good usde of accessories.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission.
The state of the s	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand.	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission.
The state of the s	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission.	Good balance between teacher's help and autonomous work. Good design and good usde of accessories.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission.
The second secon	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission.	Good balance between teacher's help and autonomous work. Good design and good usde of accessories. Appropriate commands.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission.
The state of the s	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission. Some commands are difficult to understand.	Good balance between teacher's help and autonomous work. Good design and good usde of accessories. Appropriate commands.	Team can work on its own with very little intervention from teachers. Excellent use of accessories. The robot design is very appropriate for the mission. Easy, clear and precise commands.
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ROBOT DESIGN & PROGRAMMING	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with	Good balance between teacher's help and autonomous work. Good design and good usde of accessories. Appropriate commands. Some original ideas/strategies, although teacher's intervention is necessary.	Excellent use of accessories. The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegies to overcome difficulties with little teacher's help.
and the second second	not clear. Independent work Teachers have to help in excess. Mechanic efficiency Many problems with robot design and accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is necessary. Autonomation	Teachers have to provide help or many occasions. Some problems with robot design /accessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with	Good balance between teacher's help and autonomous work. Good design and good usde of accessories. Appropriate commands. Some original ideas/strategies, although teacher's intervention is necessary.	Excellent use of accessories. The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegies to overcome difficulties with

Table Points [230] Rubric Points [39]

Total

EAM SPIRIT	1 point	2 points	3 points	4 points
	Identity		The same of the sa	
		(Mambers are enthusiastic and have fun working together.
	AND IN COLUMN TWO IS NOT THE OWNER.	Some members are enthusiastic.	together.	The team has a clear identity.
	Participation	。 1983年日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本	>=><>	(2) "特别为我们的特别。" (2)
	Participation is not	/	Participation is well	
	well balanced. Some	Participation is well balanced.	balanced and most	Participation is well balanced
	contributions are	Although some members do not		and all members contribute
	underestimated.	contribute with ideas.	jdeas.	with ideas.
	Respect		The second second	
		There are some disagreements but		
	There are frequent	members can solve their conflicts	Most members show	All members are respectful al
	arguments among members.	with little intervention by teachers.	respect to their peers, teachers, helpers.	the time towards their peers, teavhers, helpers.
	Collaboration	teachers.	teachers, helpers.	teavilets, neipers.
	Students are			
	individualistic and		/	
	competitive. They are			
		There is some cooperation		All members are helpful and
	one another.	between members.	Most members are helpful	there is a clear synergy.
	Olic Military	between members	The state of the production of	
EAM WORK	Efficiency			The state of the same
				Excellent time managment
	Poor time	.)	Good time managment.	and very clear roles. Students
	1 - (Poor time managment. Some	Clear roles. Students can	can achieve all their
and the state of the state of	not clear.	people do not fulfill their role	achieve objectives.	objectives.
	Independent work	The second secon	Good balance between	Team can work on its own
	Teachers have to help	Teachers have to provide helpon	teacher's help and	with very little intervention
	in excess.	many occasions.	autonomous work	from teachers.
	III excess.	many occasions.	autonomous work	nom ceachers.
OBOT DESIGN				
PROGRAMMING	Mechanic efficiency		A CONTRACTOR OF THE PARTY OF TH	
	Many problems with			
	robot design and	•		,
	robot design and accessories make it			Excellent use of accessories.
		Some problems with robot design	Good design and good	Excellent use of accessories. The robot design is very
	accessories make it	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	
	accessories make it difficult to fulfill			The robot design is very
	accessories make it difficult to fulfill mission. Programmin quality Too many commands.	/accessories during mission.		The robot design is very appropriate for the mission
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to	/accessories during mission. Some commands are difficult to	usde of accessories.	The robot design is very appropriate for the mission. Easy, clear and precise
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand.	/accessories during mission.		The robot design is very appropriate for the mission
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation	/accessories during mission. Some commands are difficult to	usde of accessories.	The robot design is very appropriate for the mission. Easy, clear and precise
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not	/accessories during mission. Some commands are difficult to	Appropriate commands.	The robot design is very appropriate for the mission. Easy, clear and precise
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or	/accessories during mission. Some commands are difficult to understand.	Appropriate commands. Some original	The robot design is very appropriate for the mission. Easy, clear and precise commands.
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop	Appropriate commands. Some original ideas/strategies, although	The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegic
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with	Appropriate commands. Some original ideas/strategies, although teacher's intervention is	The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegic to overcome difficulties with
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop	Appropriate commands. Some original ideas/strategies, although	The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegic
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with	Appropriate commands. Some original ideas/strategies, although teacher's intervention is	The robot design is very appropriate for the mission. Easy, clear and precise commands. Many original ideas/startegie to overcome difficulties with
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is necessary. Automorphism Pilot needs to	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with teacher's help.	Appropriate commands. Some original ideas/strategies, although teacher's intervention is necessary.	The robot design is very appropriate for the mission Easy, clear and precise commands. Many original ideas/startegic to overcome difficulties with little teacher's help.
	accessories make it difficult to fulfill mission. Programmin quality Too many commands. Difficult to understand. Innovation The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	Jaccessories during mission. Some commands are difficult to understand. The team managed to develop some original ideas/strategies with	Appropriate commands. Some original ideas/strategies, although teacher's intervention is necessary.	The robot design is very appropriate for the mission Easy, clear and precise commands. Many original ideas/startegic to overcome difficulties with little teacher's help.

Table Points [75]
Rubric Points [34]

Total

TEAM SPIRIT	1 point Identity	2 points	3 points	4 points
	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Mambers are enthusiastic and have fun working together. The tea m has a clear identity
	Participation	1963年初,他们所以为一种的数据	斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯斯	
	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute wth ideas.	Participation is well balanced and all members contribute with ideas
	Respect	信息 日本 医甲基氏 医甲基甲基氏	一位是中国中国的国际	
	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peets, teachers, helpers.	All members are respectful all the time towards their peers teavhers, helpers.
			MARKET CONTRACTOR	The second secon
	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful	All members are helpful and there is a clear synergy.
TEAM WORK	Efficiency	建 双三位的 (2010年)	THE PROPERTY OF	A STATE OF THE STA
	Poor time managment. Roles are not clear.	Poor time managment. Some people do not fulfill their role.	Good time managment Clear roles. Students can achieve objectives.	Excellent time managment and very clear roles. Students can achieve all their objectives
	Independent work		A STATE OF THE STA	经产工公司公司基础的企业
	Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work	Team can work on its own with very little intervention from teachers.
ROBOT DESIGN				
& PROGRAMMING	Mechanic efficiency		The second second second	
& PROGRAMMING	Many problems with robot design and			
	accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good usde of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	Programmin quality	在其他位置的 學 经 经 经 经 经 经 经 经 经 经 经 经 经 经 经 经 经 经		The Court of the C
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	Innovation	は他 「		
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.		Many original ideas/startegic to overcome difficulties with little teacher's help.
	Autonomation	公司 6000000000000000000000000000000000000	建筑 医	
	Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recovery reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks withou

Table Points 190)

Rubric Points 135

Total