

Team 1 Candela  
Amistia  
Lucija  
Artemis Delaig

Spanish  
Challenge  
Part 1

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Motivation</b>	Very little enthusiasm	Some members are enthusiastic	Members are enthusiastic and have fun working together	Members are enthusiastic and have fun working together. The team has a clear identity.
<b>Participation</b>	Participation is not well balanced. Some contributions are underutilized	Participation is well balanced although some members do not contribute with ideas	Participation is well balanced and most members contribute with ideas	Participation is well balanced and all members contribute with ideas
<b>Respect</b>	There are frequent arguments among members	There are some disagreements but members can solve their conflicts with little intervention by teachers	Most members show respect to their peers, teachers, helpers	All members are respectful all the time towards their peers, teachers, helpers
<b>Collaboration</b>	Students are individualistic and competitive. They are not capable of helping one another	There is some cooperation between members	Most members are helpful	All members are helpful and there is a clear synergy
<b>TEAM WORK</b>	<b>Efficiency</b> Poor time management. Roles are not clear	Poor time management. Some people do not fulfill their role	Good time management. Clear roles. Students can achieve objectives	Excellent time management and very clear roles. Students can achieve all their objectives
	<b>Independent work</b> Teachers have to help in excess	Teachers have to provide help on many occasions	Good balance between teacher's help and autonomous work	Team can work on its own with very little intervention from teachers
<b>ROBOT DESIGN &amp; PROGRAMMING</b>	<b>Mechanic efficiency</b> Many problems with robot design and accessories make it difficult to fulfill mission	Some problems with robot design /accessories during mission	Good design and good use of accessories	Excellent use of accessories. The robot design is very appropriate for the mission
	<b>Programmin quality</b> Too many commands. Difficult to understand	Some commands are difficult to understand	Appropriate commands	Easy, clear and precise commands
	<b>Innovation</b> The team does not develop any ideas or strategies. A lot of help from teachers is necessary	The team managed to develop some original ideas/strategies with teacher's help	Some original ideas/strategies, although teacher's intervention is necessary	Many original ideas/strategies to overcome difficulties with little teacher's help
	<b>Automation</b> Pilot needs to reset/recover robot very frequently	Pilot sometimes needs to recover/reset robot	Pilot occasionally needs to recover/reset robot	Robot performs tasks without pilot's intervention

32 points

30 points on

Team 2  
Yanki, Mireia, Kaja, Veronika, Maria

Spanish  
Challenge Part 1

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>				
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together	Members are enthusiastic and have fun working together. The team has a clear identity.	
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.	
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.	
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.	
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.	
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.	
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.	
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.	
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/startegies to overcome difficulties with little teacher's help.	
<b>Automation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/ reset robot.	Robot performs tasks without pilot's intervention.	

28

Gr Maya Papanastasiou  
 Sp Sergio Pinero  
 Tu Umur Kog  
 Bl Piotr Filip

Sl Nina Spielmanova  
 Team Number 3  
 Spanish Challenge  
 Part 1.

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>		✓		
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. The team has a clear identity.
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas. ✓	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers. ✓
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members. ✓	Most members are helpful.	Most members are helpful.	All members are helpful and there is a clear synergy.
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role. ✓	Good time management. Clear roles. Students can achieve objectives.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work. ✓	Good balance between teacher's help and autonomous work. ✓	Team can work on its own with very little intervention from teachers.
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission. ✓
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands. ✓	Appropriate commands. ✓	Easy, clear and precise commands. ✓
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/strategies to overcome difficulties with little teacher's help. ✓
<b>Autonomation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/reset robot.	Pilot occasionally needs to recover/reset robot. ✓	Pilot occasionally needs to recover/reset robot. ✓	Robot performs tasks without pilot's intervention.

Later fish - 5  
 4 items to recycle

2:40

99 rubric

~~95 points~~  
 55 points

(14) Stanislav Szweczyk  
 Georgia Provatoy  
 Yasin Burma  
 Kristina Besslerová  
 Martinez  
 Pau

# Spanish Challenge part 1

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>				
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. ✓	Members are enthusiastic and have fun working together. The team has a clear identity. ✓
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and most members contribute with ideas. ✓	Participation is well balanced and all members contribute with ideas. ✓
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	Most members show respect to their peers, teachers, helpers. ✓	All members are respectful all the time towards their peers, teachers, helpers. ✓
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	Most members are helpful. ✓	All members are helpful and there is a clear synergy. ✓
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Good time management. Clear roles. Students can achieve objectives. ✓	Excellent time management and very clear roles. Students can achieve all their objectives. ✓
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Good balance between teacher's help and autonomous work. ✓	Team can work on its own with very little intervention from teachers. ✓
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Good design and good use of accessories. ✓	Excellent use of accessories. The robot design is very appropriate for the mission. ✓
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Appropriate commands. ✓	Easy, clear and precise commands. ✓
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Some original ideas/strategies, although teacher's intervention is necessary. ✓	Many original ideas/startegies to overcome difficulties with little teacher's help. ✓
<b>Automation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Pilot occasionally needs to recover/reset robot. ✓	Robot performs tasks without pilot's intervention. ✓

70

40 + 30

Team 5

Maria Bosh  
 Vicky DZAKOVA  
 Alinda Gelik  
 Patrycja Zachara  
 Kyriaki Papadopoulou

Spanish Challenge  
 Part 1

TEAM SPIRIT	1 point	2 points	3 points	4 points
TEAM SPIRIT	<b>Identity</b>			
	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together	Members are enthusiastic and have fun working together. The team has a clear identity.
	<b>Participation</b>			
	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.	
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful	All members are helpful and there is a clear synergy.	
TEAM WORK	<b>Efficiency</b>			
	Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.
	<b>Independent work</b>			
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.	
ROBOT DESIGN & PROGRAMMING	<b>Mechanic efficiency</b>			
	Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	<b>Programmin quality</b>			
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	<b>Innovation</b>			
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/startegies to overcome difficulties with little teacher's help.
<b>Autonomation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.	

~~33~~ Rubrick  
 33

Team 1

Spanish Challenge Part 2

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>				
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. The team has a clear identity.	
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.	
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.	
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.	
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.	
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.	
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.	
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.	
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/strategies to overcome difficulties with little teacher's help.	
<b>Autonomation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.	

Table Points: 5

Rubric Points 35

total: 40

Team 2

Spanish Challenge  
part 2

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>			Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. The team has a clear identity.
	Very little enthusiasm	Some members are enthusiastic.		
<b>Participation</b>	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
<b>Respect</b>	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.
<b>Collaboration</b>	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.
<b>TEAM WORK</b>	<b>Efficiency</b>			
	Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.
	<b>Independent work</b>			
	Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
<b>ROBOT DESIGN &amp; PROGRAMMING</b>	<b>Mechanic efficiency</b>			
	Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	<b>Programmin quality</b>			
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	<b>Innovation</b>			
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/strategies to overcome difficulties with little teacher's help.
	<b>Automation</b>			
	Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.

Table points 65

Rubric points 37

Total 102

Team 3

Spanish Challenge  
part 2

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>				
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. The team has a clear identity.
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	Most members are helpful.	All members are helpful and there is a clear synergy.
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Appropriate commands.	Easy, clear and precise commands.
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/strategies to overcome difficulties with little teacher's help.
<b>Autonomation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.

Table Points 230

Rubric Points 39

Total 269



Team 4

Spanish Challenge  
part 2

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>				
Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together.	The team has a clear identity.
<b>Participation</b>				
Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.	
<b>Respect</b>				
There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.	
<b>Collaboration</b>				
Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.	
<b>TEAM WORK</b>				
<b>Efficiency</b>				
Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.	
<b>Independent work</b>				
Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.	
<b>ROBOT DESIGN &amp; PROGRAMMING</b>				
<b>Mechanic efficiency</b>				
Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.	
<b>Programmin quality</b>				
Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.	
<b>Innovation</b>				
The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/startegies to overcome difficulties with little teacher's help.	
<b>Automation</b>				
Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/ reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.	

Table Points 175

Rubric Points 134

Total 1109

Team 5

Spanish Challenge  
Part 2

TEAM SPIRIT	1 point	2 points	3 points	4 points
<b>Identity</b>	Very little enthusiasm	Some members are enthusiastic.	Members are enthusiastic and have fun working together.	Members are enthusiastic and have fun working together. The team has a clear identity.
<b>Participation</b>	Participation is not well balanced. Some contributions are underestimated.	Participation is well balanced. Although some members do not contribute with ideas.	Participation is well balanced and most members contribute with ideas.	Participation is well balanced and all members contribute with ideas.
<b>Respect</b>	There are frequent arguments among members.	There are some disagreements but members can solve their conflicts with little intervention by teachers.	Most members show respect to their peers, teachers, helpers.	All members are respectful all the time towards their peers, teachers, helpers.
<b>Collaboration</b>	Students are individualistic and competitive. They are not capable of helping one another.	There is some cooperation between members.	Most members are helpful.	All members are helpful and there is a clear synergy.
<b>TEAM WORK</b>	<b>Efficiency</b>			
	Poor time management. Roles are not clear.	Poor time management. Some people do not fulfill their role.	Good time management. Clear roles. Students can achieve objectives.	Excellent time management and very clear roles. Students can achieve all their objectives.
	<b>Independent work</b>			
	Teachers have to help in excess.	Teachers have to provide help on many occasions.	Good balance between teacher's help and autonomous work.	Team can work on its own with very little intervention from teachers.
<b>ROBOT DESIGN &amp; PROGRAMMING</b>	<b>Mechanic efficiency</b>			
	Many problems with robot design and accessories make it difficult to fulfill mission.	Some problems with robot design /accessories during mission.	Good design and good use of accessories.	Excellent use of accessories. The robot design is very appropriate for the mission.
	<b>Programmin quality</b>			
	Too many commands. Difficult to understand.	Some commands are difficult to understand.	Appropriate commands.	Easy, clear and precise commands.
	<b>Innovation</b>			
	The team does not develop any ideas or strategies. A lot of help from teachers is necessary.	The team managed to develop some original ideas/strategies with teacher's help.	Some original ideas/strategies, although teacher's intervention is necessary.	Many original ideas/strategies to overcome difficulties with little teacher's help.
	<b>Autonomation</b>			
	Pilot needs to reset/recover robot very frequently.	Pilot sometimes needs to recover/reset robot.	Pilot occasionally needs to recover/reset robot.	Robot performs tasks without pilot's intervention.

Table Points 190

Rubric Points 37

Total 127