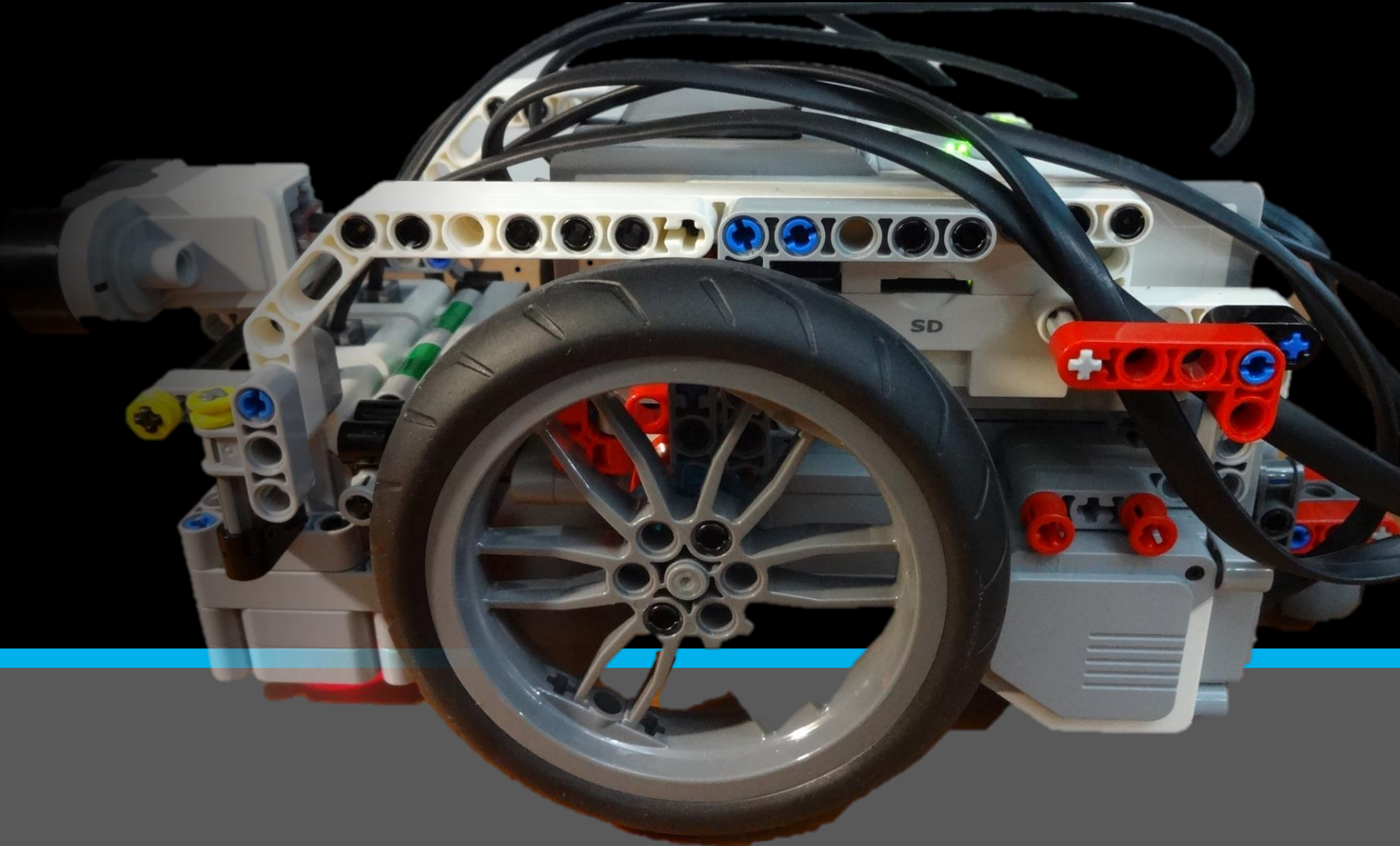


EV3 Line Follower Robot, "Samianator"



By: Vogiatzis Dimitrios, Vasileias Panagiotis, Konsta Eleni, Papatheofanous Themistoklis | Teacher: Mparekos Vasileios | School: 2o Gymnasio Samou, Greece

Purpose

Our LEGO EV3 Line Follower Robot follows the black line that has several curved turns and may split and re-join. The robot can also cope with track obstacles like objects laid on the track or line cut-offs.

from: Samos Island, Greece



- **Samos** the island of legend and beauty, in the Eastern Aegean sea on the East of Greece.
- It is well-known because of its sweet Muscat wine, the beautiful attractions and the rich history.
- Home of **Pythagoras**, the great mathematician and philosopher, and
- **Aristarchus**, the astronomer. The first person to propose the heliocentric theory.
- Archaeological developments like the Temple of goddess **Hera** and
- **Eupalinos tunnel**, the masterpiece of engineering.

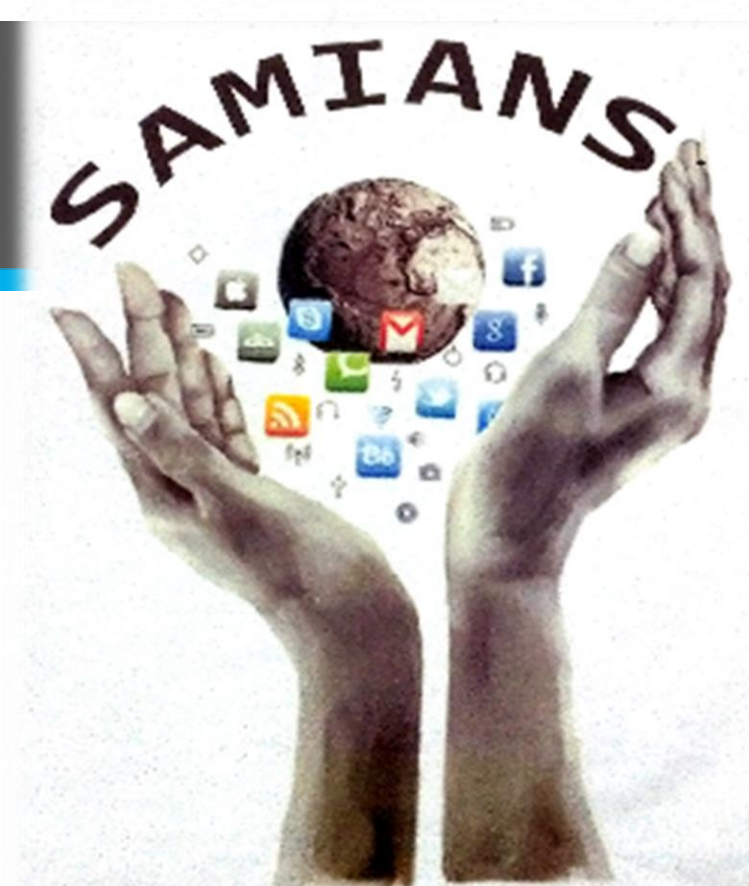
about: The Team

Our team Samians, has students aged 14 to 15 from the **Junior High School of Samos, Greece**. On our way to create the Line Follower Robot, we were helped by students who worked voluntarily on their free time.



This year, 2016-2017, our School has 185 students. Its infrastructure includes a Computer Science Lab and a courtyard which has a handball court and also 2 basketball courts.

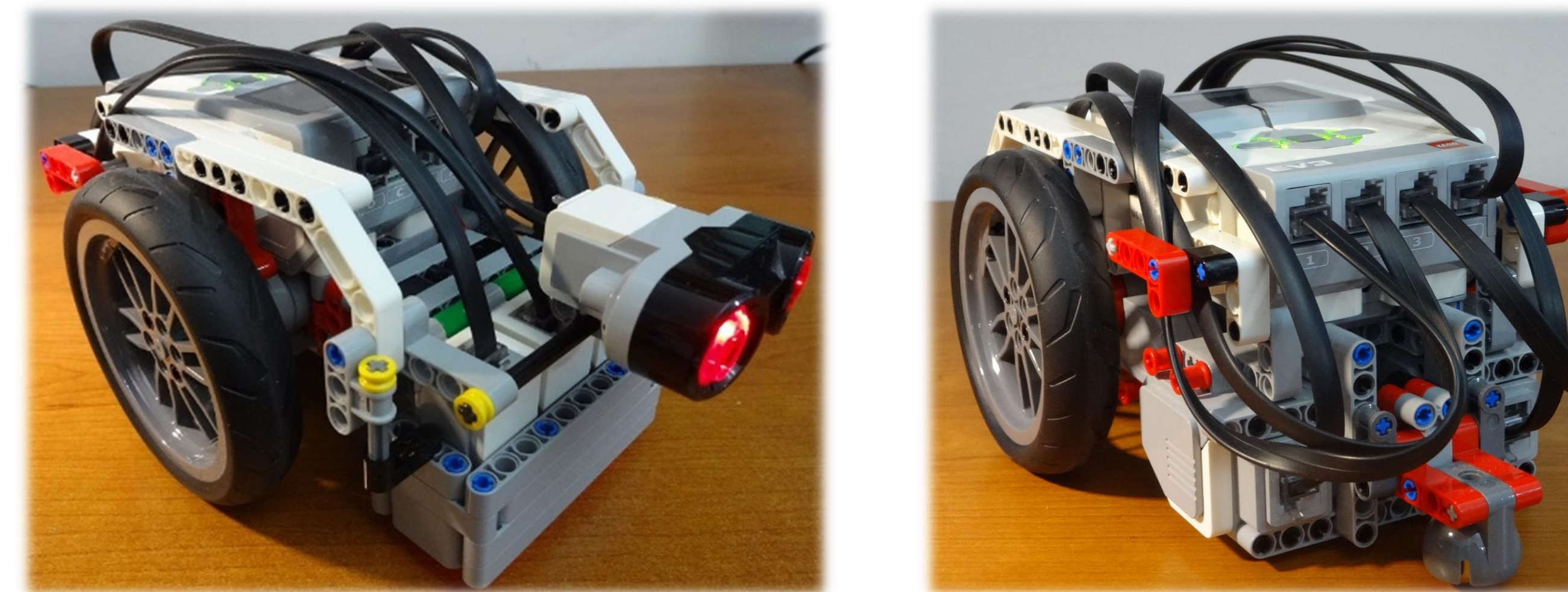
WEB <http://2gym-samou.sam.sch.gr>
Email 2gymsamo@sch.gr



Materials

Key Materials	Quantity
EV3 Intelligent Brick	1
EV3 Colour Sensor	3
EV3 Ultrasonic Sensor	1
EV3 Large Servo Motor	2
Tires from Lego Technic (42036) Motorcycle kit	2

The Robot



Design

Motors

Normal position Reversed position

Chassis Chassis

GROUND

Reversed motor position for lower center of gravity

Sensors

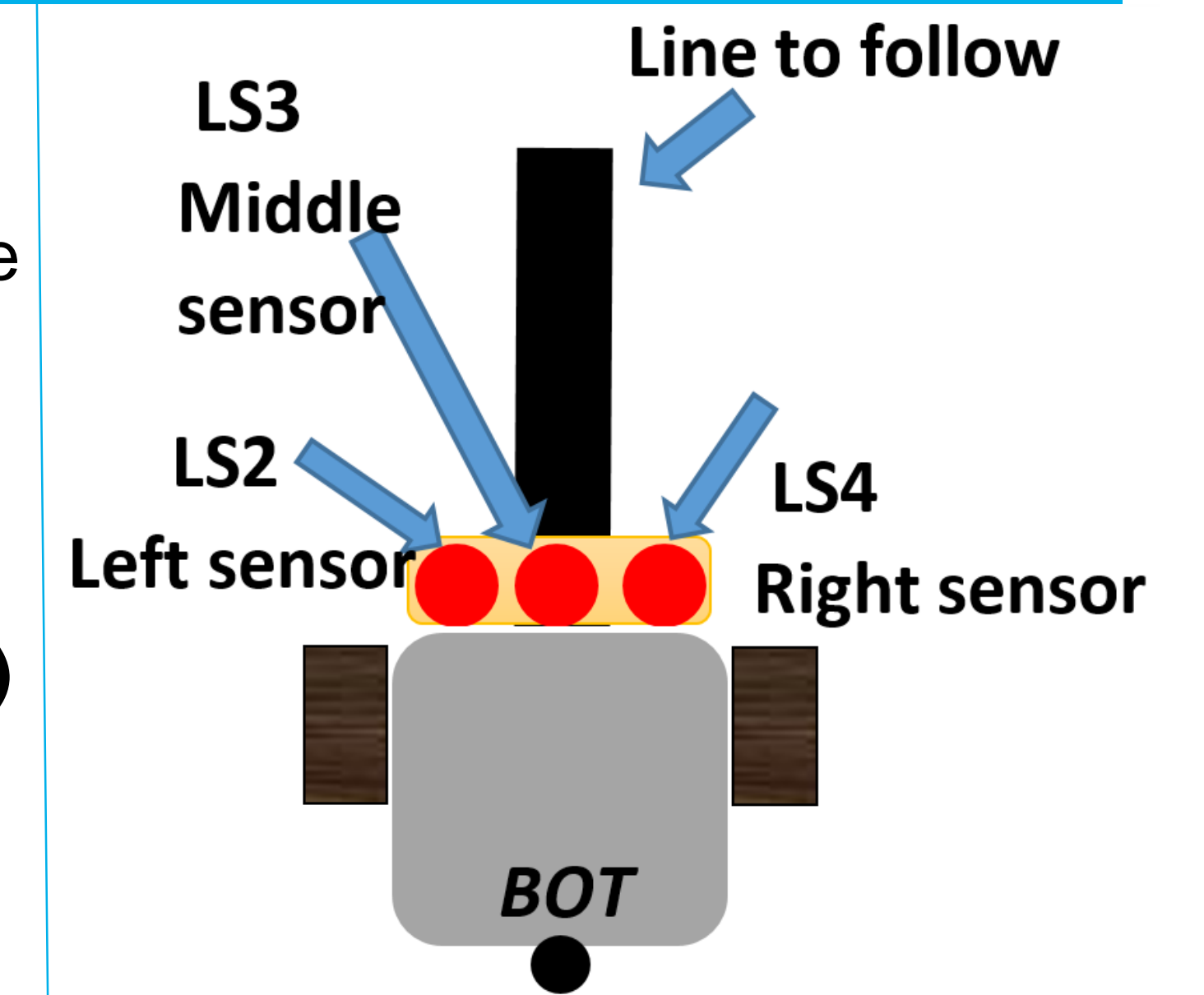
LS2 LS3 LS4

3 Light Sensors for better line following

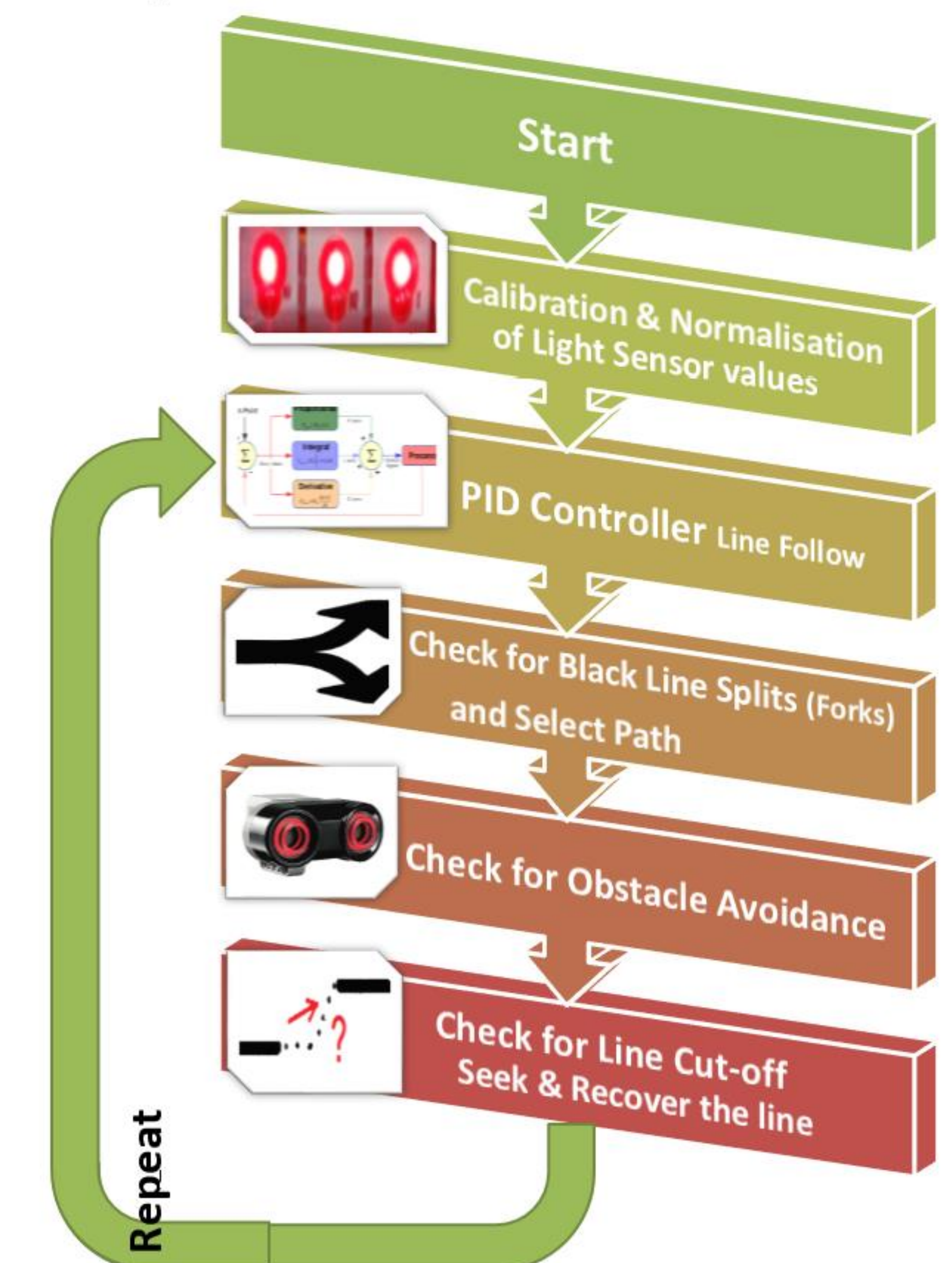
1 Ultrasonic Sensor for Obstacle Avoidance

Line Follow Principle

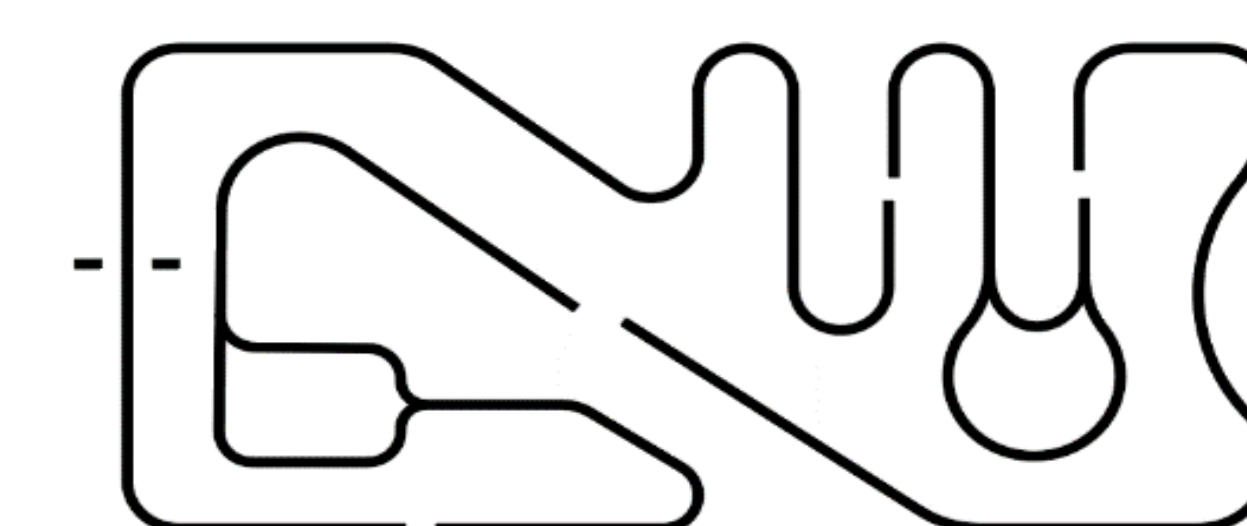
- Line Follow is based in comparing the 3 measured reflected light intensities from the Colour Sensors.
- Light Error Calculation Formula
Error = (LS2 – LS3) + (LS3 – LS4)
- Always tries to position the line in the middle sensor, ie **Error = 0**



Program Flow Diagram



Testing to some Tracks...



Robot Samianator in action!
<https://youtu.be/NJspfrxu12E>